

Current Technologies to Better Assess and Monitor Potential Glacial Hazards

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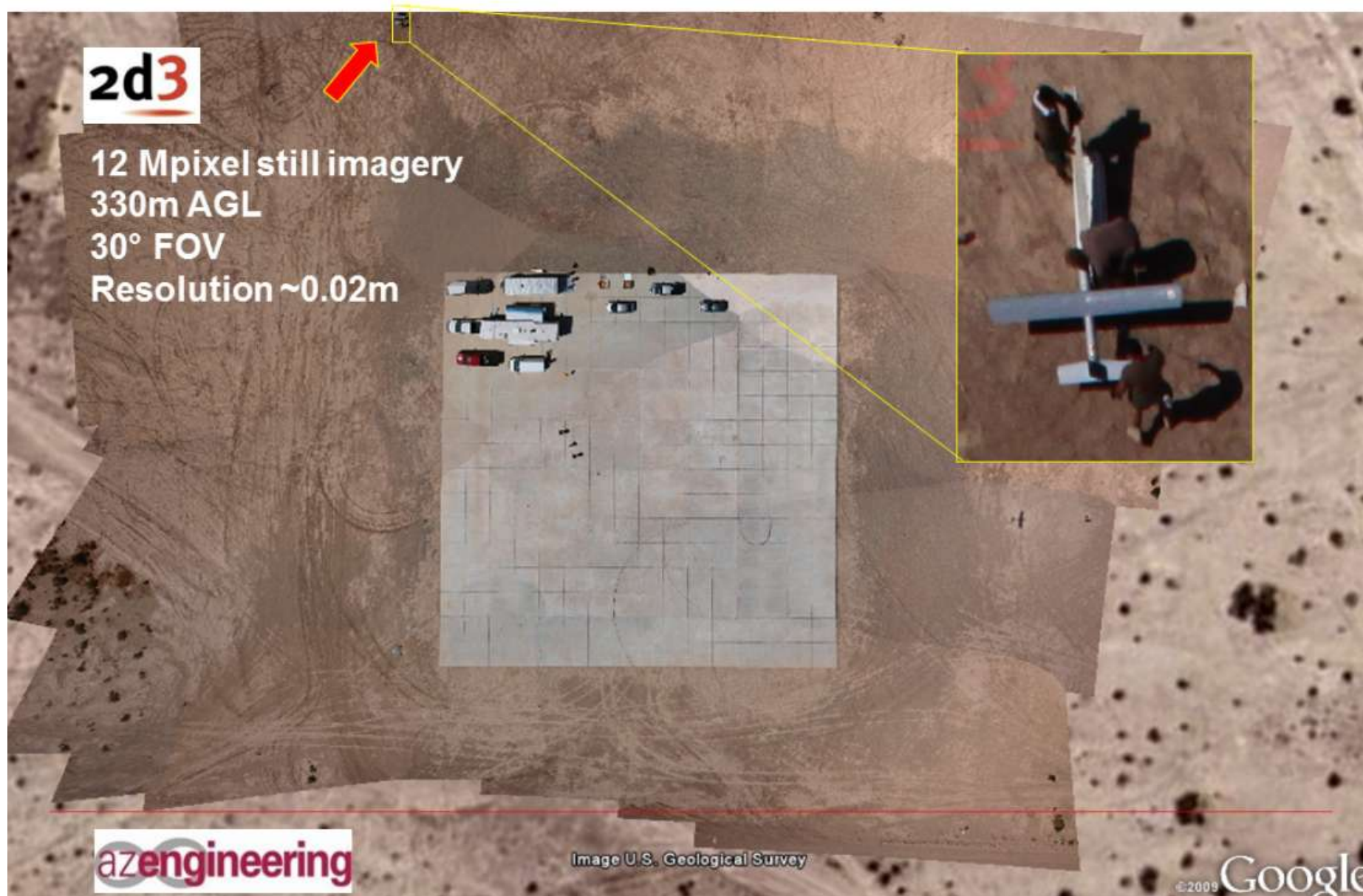
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Sensors and User Interfaces

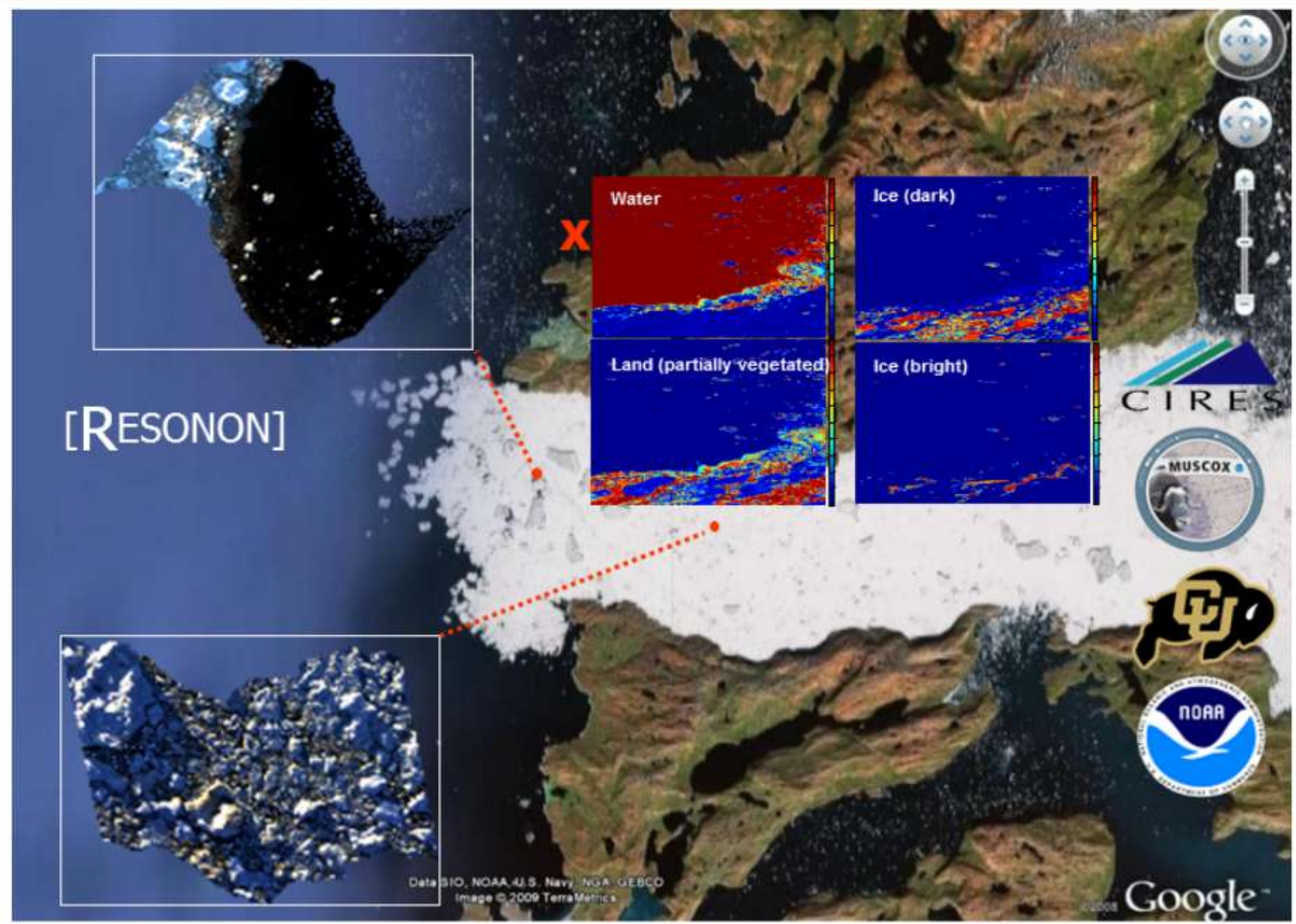
- A broad range of expeditionary sensors currently exist (<3kg)
 - Optical – EO-IR-UV, multi-spectral and hyperspectral, polarization
 - Magnetometers
 - Electromagnetic - conductivity
 - Radar, Synthetic aperture radar (SAR)
 - Gas spectrometers
 - Acoustic and sonar
 - Mass spectrometers, nuclear,
 - GPS
 - Others

- Improvements in data processing and the user interface
 - Data used for process control - hybrid control systems
 - Image mosaicing for large area mapping (pixel and geo-registering)
 - Image topographic reconstruction
 - Digital relief map (DRM)
 - Digital terrain map (DTM)
 - Digital elevation map (DEM)

EO Imaging - Mosaic with Detail (TacitView)



Hyperspectral Imagery - Greenland



Scientific Applications for Small UAV Platforms

- ◆ Mount St Helens, October 2004
- ◆ Atmospheric Brown Cloud Campaign
- ◆ Maldives (Hanimaadhoo), March 2006
 - 18 missions over Indian Ocean
 - over 125 hours of flight time
 - multiple sensors
 - synchronized stacks of 3 Mantas
 - real-time data access (partial)
- ◆ Landmark Campaign for science/UAVs
 - ◆ Korean Campaign CAPMEX 2008
 - ◆ Cheju Island S. Korea (flight certification)
 - ◆ June – September 2008
 - 75 flights, 130 hours over 32 days
 - multiple sensors, synchronized
 - atmospheric conditions “Olympics”
 - ◆ Dryden April 08 – Jan 09
 - ◆ Vandenberg November 08
 - ◆ Sea-air interfacial flux measurements



Scientific UAV Sensors

- Greenland, Kangerlassuaq, Aug 2007
- Greenland, Ilulissat Ice Fjord, July, 2008
- Sea Ice and melt pool data collections
 - Hyperspectral
 - Several others

Infer aerosol forcing and ozone radiative forcing on regional scales

- ◆ 1. Condens. particle counter (0.87kg) >10nm
- ◆ 2. Optical particle counter (0.3kg) - 0.3 - 3 μ m
- ◆ 3. Cloud condens. nuclei counter (3kg) >0.2%
- ◆ 4. Aethalometer (0.8kg) - absorbing aerosol
- ◆ 5. Cloud droplet probe (1.42kg) - 0.7 - 70 μ m
- ◆ 6. Pyranometer (0.2kg) - 305nm - 2800nm
- ◆ 7. PAR radiometer (0.03kg) - 400nm - 700nm
- ◆ 8. Spectral radiometer (0.4kg) 350 – 1150nm
- ◆ 9. Optical video camera
- ◆ 10. Ozone sensor (Korea)
- ◆ 11. LIDAR (Greenland)



Small USV Platforms – Side Scan Sonar

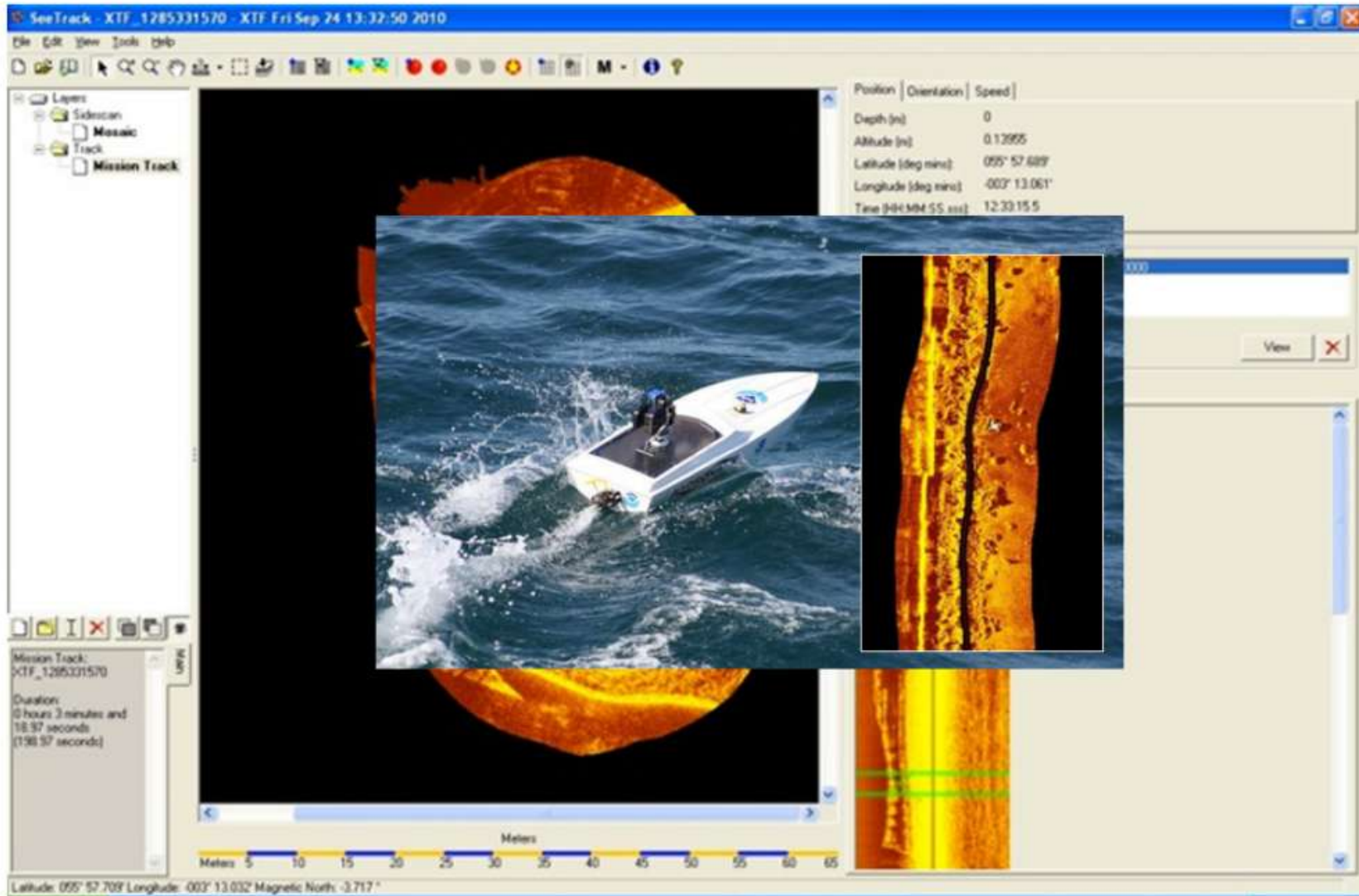
- EMILY – developed by UA Alumni (Hydronalix)
 - Large interest with media
 - <http://www.newslincolncounty.com/>
 - Currently undergoing user assessment
- HASS – Hydronalix Autonomous Security Syst.
 - Interest by NOAA – mapping and security
 - Interest by US Navy
 - Interest by DHS for security
- Side scan sonar into HASS for mapping
 - TriTech-StarFish Sonar - streaming
 - Operated through SeeByte software
 - SeeTrack software - georectifies sonar
 - Generates bathymetry data



Small USV Platforms – Safety and Science

- University of Arizona is partnering with Hydronalix
- EMILY developed as a life preserver for distressed swimmers
- Tactical capabilities
 - Approximately 1.25m in length
 - Approximately 12kg in weight
 - Duration 2 to 6 hours
 - Fully autonomous or RC
- Integrated light weight, side scan sonar
 - Linear bathymetric readout
- Integrated SeeTrack (SeeByte) software
 - Georectifies sonar
 - High resolution detail – 0.02m
 - 3D bathymetric reconstruction
- Tested in USA, Canada and Scotland



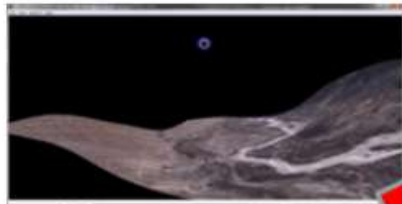


Assess Glacial Hazard – Mission 14th and 15th Oct.



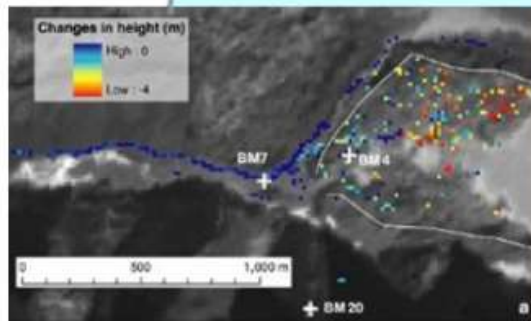
Assess Glacial Hazard – Mission 14th and 15th Oct.

- Mechanisms leading to lake support failure are poorly understood
- Potential GLOF lakes lie in remote, difficult to access environments
- Topographic maps above and below the water will be generated – baseline
- Subsequent missions will map and quantify the rate of change

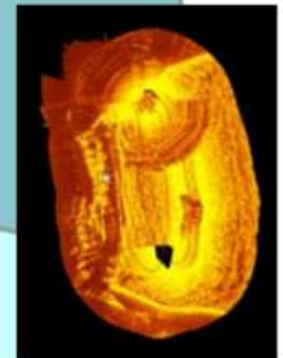
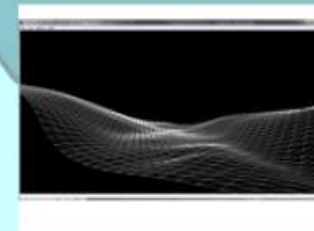


High resolution airborne video

Historical (2002 – 7)



High resolution sonar



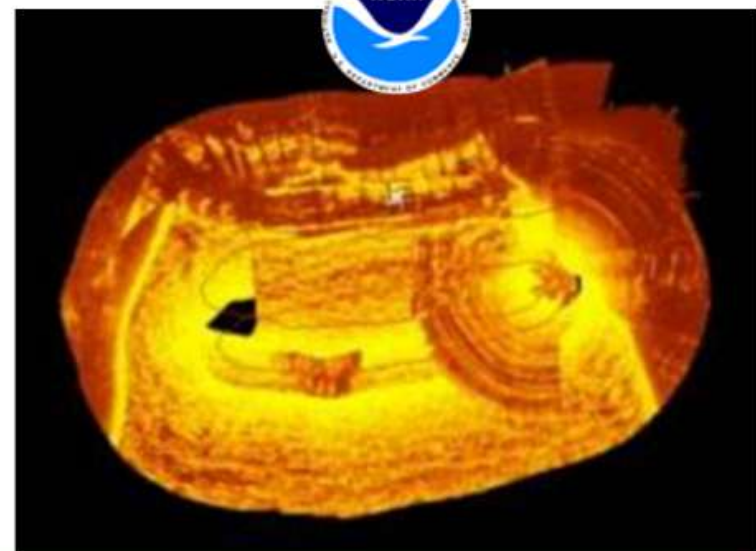
Side Scan Sonar and Software

- TriTech Side Scan Sonar

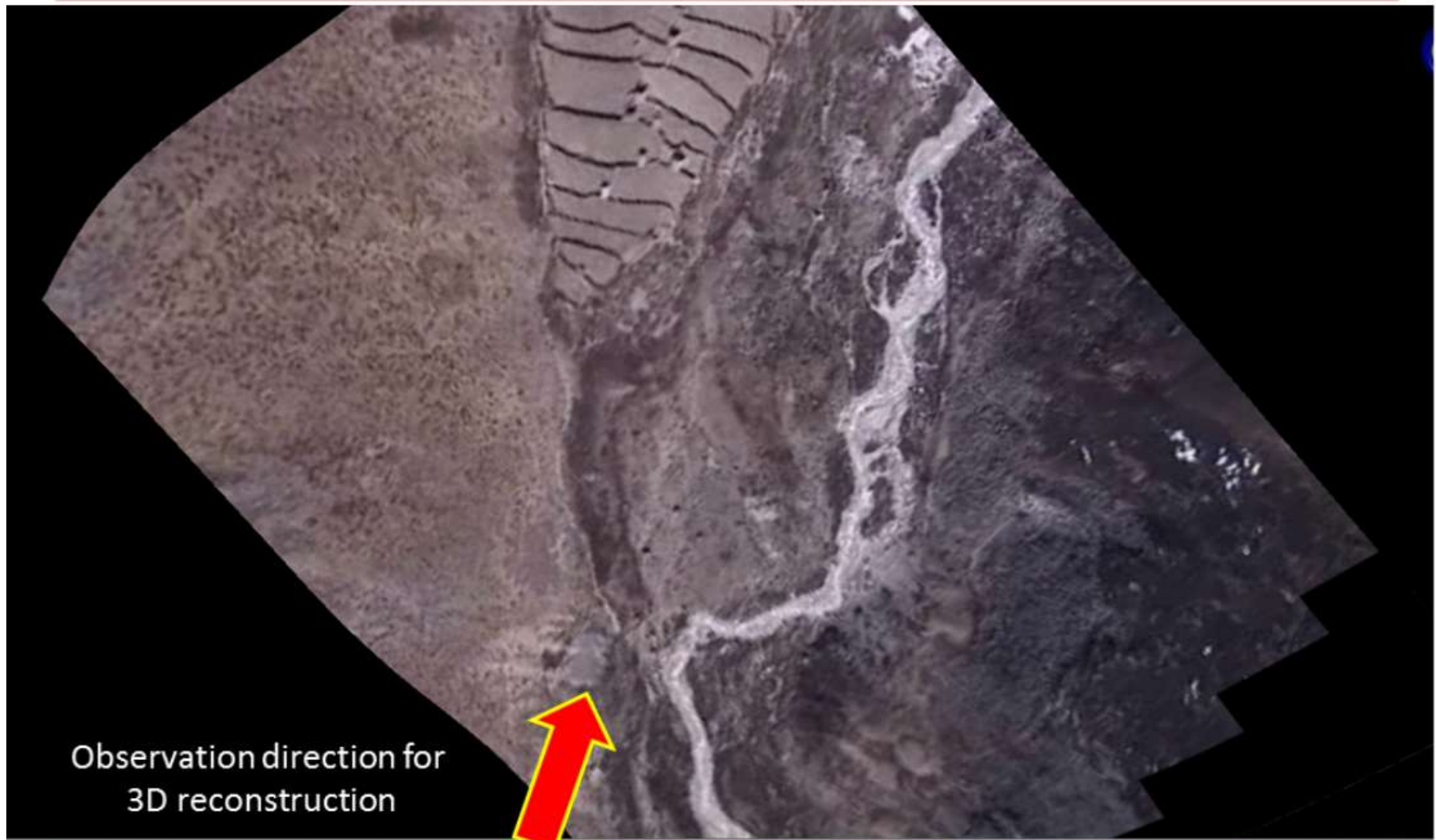
- 100m range
- Frequency sweep
- Resolution ~0.03m
- Weight about 0.5kg
- 180 degree sweep

- Integrated by SeeByte

- Processed through SeeTrack Software
- Georectified to generate bathymetry
- WiFi real time data feed



Ding Boche Village - Mosaic from April 2009

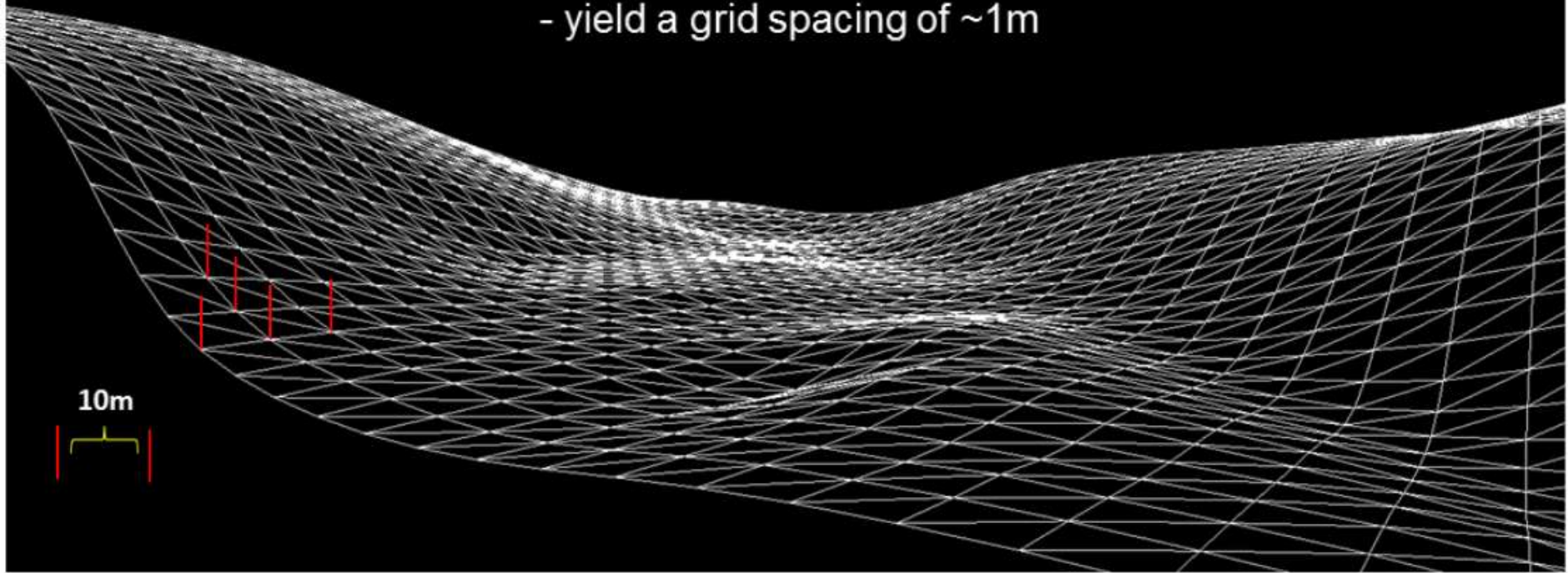


Ding Boche Village - Grid Generation April 2009

April 2009 video yielded post reconstruction grid size of approximately 10m

High resolution imagery

- 15 megapixel
- 30° FOV
- 170m AGL
- yield a grid spacing of ~1m



2d/3 sample product

